

Special Focus on Guidance, Navigation and Control

Position tracking and attitude control for quadrotors via active disturbance rejection control method.....010201(10)
Yuan YUAN, Lei CHENG, Zidong WANG & Chong SUN

UIF-based cooperative tracking method for multi-agent systems with sensor faults.....010202(14)
Yingrong YU, Siting PENG, Xiwang DONG, Qingdong LI & Zhang REN

Docking navigation method for UAV autonomous aerial refueling.....010203(16)
Delin LUO, Jiang SHAO, Yang XU & Jinpeng ZHANG

Cooperative geometric localization for a ground target based on the relative distances by multiple UAVs.....010204(10)
Yaohong QU, Feng ZHANG, Xiwei WU & Bing XIAO

Cooperative trajectory optimization for unmanned aerial vehicles in a combat environment.....010205(3)
Tingting BAI & Daobo WANG

Trajectory optimization for RLV in TAEM phase using adaptive Gauss pseudospectral method010206(3)
Qi DONG & Chaofan ZHANG

Taxiing stability verification and airworthiness certification for amphibious aircraft.....010207(3)
Xufei HE & Jianliang AI

Control and dynamics analysis for miniature autogyro and compound autogyro010208(3)
Zhihao CAI, Ningjun LIU, Jiang ZHAO & Yingxun WANG

RESEARCH PAPER

A convergence analysis for a class of practical variance-reduction stochastic gradient MCMC.....012101(13)
Changyou CHEN, Wenlin WANG, Yizhe ZHANG, Qinliang SU & Lawrence CARIN

Controllability analysis of multi-agent systems with switching topology over finite fields012201(15)
Zehuan LU, Lin ZHANG & Long WANG

FVO: floor vision aided odometry012202(13)
Wenjun LV, Yu KANG & Jiahu QIN

Performance analysis of switched linear systems under arbitrary switching via generalized coordinate transformations012203(11)
Meili LIN & Zhendong SUN

Basic theory and stability analysis for neutral stochastic functional differential equations with pure jumps.....012204(15)
Mengling LI, Feiqi DENG & Xuerong MAO

On strong structural controllability and observability of linear time-varying systems: a constructive method012205(14)
Shaoyuan LI, Jianbin MU & Yishi WANG

Extended state observer-based third-order sliding mode finite-time attitude tracking controller for rigid spacecraft012206(16)
Chutipphon PUKDEBOON

Symmetry-based decomposition of finite games012207(13)
Changxi LI, Fenghua HE, Ting LIU & Daizhan CHENG

Further results on dynamic-algebraic Boolean control networks012208(14)
Sen WANG, Jun-E FENG, Yongyuan YU & Jianli ZHAO

Efficient quantum state transmission via perfect quantum network coding.....012501(14)
Zhen-Zhen LI, Gang XU, Xiu-Bo CHEN, Zhiguo QU, Xin-Xin NIU & Yi-Xian YANG

MOOP

Unmanned aerial systems coordinate target allocation based on wolf behaviors.....014201(3)
Haibin DUAN, Qing YANG, Yimin DENG, Pei LI, Huaxin QIU, Tianjie ZHANG, Daifeng ZHANG,
Mengzhen HUO & Yankai SHEN

HIGHLIGHT

A formally verified transformation to unify multiple nested clocks for a Lustre-like language.....012801(3)
Gang SHI, Yucheng ZHANG, Shu SHANG, Shengyuan WANG, Yuan DONG & Pen-Chung YEW

LETTER

A clustering-based approach for mining dockerfile evolutionary trajectories.....019101(3)
Yang ZHANG, Huaimin WANG & Vladimir FILKOV

How security bugs are fixed and what can be improved: an empirical study with Mozilla.....019102(3)
Xiaobing SUN, Xin PENG, Kai ZHANG, Yang LIU & Yuanfang CAI

Identifying RNA-binding proteins using multi-label deep learning019103(3)
Xiaoyong PAN, Yong-Xian FAN, Jue JIA & Hong-Bin SHEN

Learning discriminative and invariant representation for fingerprint retrieval019104(3)
Dehua SONG, Ruilin LI, Fandong ZHANG & Jufu FENG

Minimum input selection of reconfigurable architecture systems for structural controllability019201(3)
Ting BAI, Shaoyuan LI & Yuanyuan ZOU

Multidimensional zero-crossing interval points: a low sampling rate acoustic fingerprint recognition method.....019202(3)
Xianghu YUE, Fang DENG & Yue XU

Backstepping control of a quadrotor unmanned aerial vehicle based on multi-rate sampling.....019203(3)
Fakui WANG, Weisheng CHEN, Hao DAI, Jing LI & Jinping JIA