

Hilger-type impulsive differential inequality and its application to impulsive synchronization of delayed complex networks on time scales

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Received 14 July 2017/Revised 17 October 2017/Accepted 30 November 2017/Published online 19 April 2018

Citation Huang Z K, Cao J D, Raffoul Y N. Hilger-type impulsive differential inequality and its application to impulsive synchronization of delayed complex networks on time scales. *Sci China Inf Sci*, 2018, 61(7): 078201, https://doi.org/10.1007/s11432-017-9304-7

The synchronization and synchronous control of complex networks [1] have rich dynamics and are lately receiving much needed attention [2–6]. Owing to the major role that impulsive control plays [6] in investigating synchronization problems and impulsive synchronization in dynamical networks, researchers have devoted more time researching them [2–6]. However, most of the existing literature concerning impulsive effects are confined to continuous or discrete time domains [2, 6]. In this article, we establish Hilger-type impulsive differential inequality [7] which is a useful technical tool in investigating complex dynamic systems under impulsive disturbances. Meanwhile, we obtain scale-type synchronization criteria for complex networks with multiple delays. Our results not only improve existing results but also offer a new approach to understand the similarities and differences between synchronization of continuous-time and discrete-time cases, under impulsive effects.

Preliminaries. We recall some definitions and preliminary results [8] first. Let \mathbb{T} be a nonempty closed subset of \mathbb{R} . The forward and backward jump operators $\sigma, \rho: \mathbb{T} \rightarrow \mathbb{T}$ and the graininess $\mu: \mathbb{T} \rightarrow \mathbb{R}^+$ are defined, respectively, by $\sigma(t) = \inf\{s \in \mathbb{T} : s > t\}$, $\rho(t) = \sup\{s \in \mathbb{T} : s < t\}$

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and $\mu(t) = \sigma(t) - t$. A point $t \in \mathbb{T}$ is called left-dense if $t > \inf \mathbb{T}$ and $\rho(t) = t$, left-scattered if $\rho(t) < t$, right-dense if $t < \sup \mathbb{T}$ and $\sigma(t) = t$, and right-scattered if $\sigma(t) > t$. If \mathbb{T} has a left-scattered maximum m , $\mathbb{T}^k = \mathbb{T} - \{m\}$, otherwise $\mathbb{T}^k = \mathbb{T}$. The notation $[a, b]_{\mathbb{T}}$ means $[a, b]_{\mathbb{T}} = [a, b] \cap \mathbb{T}$, where $b \leq +\infty$. $f: \mathbb{T} \rightarrow \mathbb{R}$ is said to be rd-continuous provided it is continuous at right-dense points in \mathbb{T} and its left-side limits exist (finite) at left-dense points in \mathbb{T} . Let $C_{\text{rd}}(\Omega, \mathbb{R})$ be the set of all rd-continuous functions on $\Omega \subseteq \mathbb{T}$, $C_{\text{rd}} := C_{\text{rd}}(\mathbb{T}, \mathbb{R})$ and $C_{\text{rd}}^{\tau} := C_{\text{rd}}([-\tau, 0]_{\mathbb{T}}, \mathbb{R})$. The (delta) derivative of $f: \mathbb{T} \rightarrow \mathbb{R}$ is defined by

$$f^{\Delta}(t) = \frac{f(\sigma(t)) - f(t)}{\sigma(t) - t},$$

if f is continuous at t and t is right-scattered. If t is not right-scattered, the derivative is defined by

$$f^{\Delta}(t) = \lim_{s \rightarrow t} \frac{f(\sigma(t)) - f(s)}{\sigma(t) - s} = \lim_{s \rightarrow t} \frac{f(t) - f(s)}{t - s},$$

provided this limit exists. A function $p: \mathbb{T} \rightarrow \mathbb{R}$ is said to be regressive if and only if $1 + \mu(t)p(t) \neq 0$ for all $t \in \mathbb{T}^k$. Let \mathcal{R} be the set of all rd-continuous and regressive functions on \mathbb{T} and $\mathcal{R}^+ = \{p \in \mathcal{R} : 1 + \mu(t)p(t) > 0 \text{ for all } t \in \mathbb{T}\}$. Denote \mathcal{M} as the set

of matrices with appropriate dimension and \mathcal{M}_E as the set of matrices with equal sum of each row. I_n is the identity matrix of order n .

System description and Hilger-type impulsive differential inequality. Consider the impulsive complex networks on time scales

$$\begin{cases} x^\Delta(t) = (I_N \otimes A)x(t) + \mathcal{F}(x(t), x(t - \tau(t))) \\ \quad + c(B \otimes \Gamma) \int_{t-\delta(t)}^t H(t-s)x(s)\Delta s, \quad (1) \\ \Delta x(t_k) = (I_N \otimes C_k)(\eta^k \otimes I_n)x(t_k), \end{cases}$$

where $t \in \mathbb{T}$, the initial condition is given by $x(s) = (x_1(s), x_2(s), \dots, x_n(s))^T = \psi(s)$ ($s \in [-\tau, 0]_{\mathbb{T}}$), and $\mathcal{F}(x(t), x(t - \tau(t))) := (F(x_1(t), x_1(t - \tau(t))), \dots, F(x_N(t), x_N(t - \tau(t))))^T$. A is a constant $n \times n$ matrix, $c > 0$ is a coupling strength, Γ is an inner coupling matrix, and $B = (b_{ij})_{N \times N} \in \mathcal{M}_E$ is a coupling matrix. $0 \leq \tau(t) \leq \tau_M$, $0 \leq \delta(t) \leq \delta_M$. $H : [0, \delta_M]_{\mathbb{T}} \rightarrow \mathbb{R}^+$ is a nonnegative function and $\int_0^{\delta_M} H(w)\Delta w < +\infty$. The map $F : \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}^n$ is continuous and satisfies $\|F(v, v_1) - F(\hat{v}, \hat{v}_1)\| \leq K\|v - \hat{v}\| + K_\tau\|v_1 - \hat{v}_1\|$. Let $\eta^k := (\eta_{ij}^k)_{N \times N}$ be the impulsive instant sequence $\{t_k\}_{k=1}^\infty \subset [t_0, +\infty)_{\mathbb{T}}$ that satisfies $0 = t_0 < t_1 < t_2 < \dots$, $\lim_{k \rightarrow \infty} t_k = \infty$, C_k be a $n \times n$ constant matrix. We assume all impulsive points are right-dense and $\tau := \max\{\tau_M, \delta_M\}$. Below, we state the technical lemma for Hilger-type impulsive differential inequality.

Lemma 1. Let $v(t)$ satisfy

$$\begin{cases} v^\Delta(t) = (a + b\mu(t))v(t), \\ v(t_k^+) = a_k v(t_k), \quad k = 1, 2, \dots, \end{cases} \quad (2)$$

where $a, b, a_k \in \mathbb{R}$. For any $t \in [t_{k-1}, t_k]_{\mathbb{T}}$, if there exists a constant $\alpha \in \mathbb{R}$ such that

$$(H_1) : \begin{cases} a + b\mu(t) \in \mathcal{R}^+, \sup_{k \in \mathbb{N}} \left\{ \frac{\log a_k}{t_k - t_{k-1}} \right\} < \alpha, \\ \frac{\log a_k}{t_k - t_{k-1}} \mu(t) \leq \log(1 + \alpha\mu(t)) \end{cases}$$

holds, $v(t) \leq a^\sharp v(t_0)e_{\alpha \oplus (a+b\mu)}(t, t_0)$ for all $t \in [t_0, +\infty)_{\mathbb{T}}$, where $a^\sharp := \max_{k \in \mathbb{N}}\{1/a_k, 1\}$.

Discussion 1.

• When $\mathbb{T} = \mathbb{R}$, $a + b\mu(t) \in \mathcal{R}^+$ and $\alpha > -\frac{1}{\mu(t)}$ can be removed. Then (H_1) is reduced to

$$(\widehat{H}_1) : \sup_{k \in \mathbb{N}} \left\{ \frac{\log a_k}{t_k - t_{k-1}} \right\} \leq \alpha,$$

and hence $v(t) \leq a^\sharp v(t_0)e^{(\alpha+a)(t-t_0)}$ for all $t \in [t_0, +\infty)$.

• If all points in \mathbb{T} are right-scattered, because $\alpha\mu(t) > \log(1 + \alpha\mu(t))$, (H_1) is reduced to

$$(\widetilde{H}_1) : \begin{cases} a + b\mu(t) \in \mathcal{R}, \quad t \in [t_0, +\infty)_{\mathbb{T}}, \\ \frac{\log a_k}{t_k - t_{k-1}} \mu(t) \leq \log(1 + \alpha\mu(t)), \end{cases}$$

where $t \in [t_{k-1}, t_k]_{\mathbb{T}}$. As $\mathbb{T} = \mathbb{Z}$, (\widetilde{H}_1) implies that $1 + a + b \neq 0$ and $a_k \leq (1 + \alpha)e^{t_k - t_{k-1}}$. Hence one gets $v(t) \leq a^\sharp v(t_0) \exp \int_{t_0}^t \log(1 + a + b + \alpha + \alpha(a + b))\Delta s$.

Proposition 1. For any arbitrary $\epsilon > 0$, let $v(t)$ be the unique solution of

$$\begin{cases} v^\Delta(t) = (a + b\mu(t))v(t) + cv(t - \tau(t)) \\ \quad + d \int_{t-\delta(t)}^t H(t-s)v(s)\Delta s + \epsilon, \quad (3) \\ v(t_k^+) = a_k v(t_k), \end{cases}$$

with $v(s) = \psi(s) \in C_{rd}([t_0 - \tau, t_0]_{\mathbb{T}}, \mathbb{R})$. Assume there exist constants α and $\lambda < 0$ such that (H_1) and

$$(H_2) : \begin{cases} 1 + \lambda\mu(s) > 0, \\ 1 \geq a^\sharp \sup_{s \in [t_0, +\infty)_{\mathbb{T}}} \left\{ \frac{ce_{\ominus\lambda}(s, s - \tau(s))}{\lambda - p(s)} \right. \\ \quad \left. + \frac{de_{\ominus\lambda}(s, s - \delta(s))}{\lambda - p(s)} \int_0^{\delta(s)} H(w)\Delta w \right\} \\ > 0, \\ \Xi := \inf_{s \in [t_0, +\infty)_{\mathbb{T}}} \{-p(s)\} \\ > a^\sharp \left(c + d \int_0^{\delta_M} H(w)\Delta w \right) \end{cases}$$

hold, where $p(s) := \alpha \oplus (a + b\mu(s))$ and $a^\sharp := \max_{k \in \mathbb{N}}\{1/a_k, 1\}$. Then we have (i) $v(t) = \mathcal{G}(t, t_0)\psi(t_0) + \int_{t_0}^t \mathcal{G}(t, \sigma(s))[cv(s - \tau(s)) + d \int_{s-\delta(s)}^s H(s-w)v(w)\Delta w + \epsilon]\Delta s$, where $\mathcal{G}(t, t_0) = \prod_{t_0 < t_k < t} a_k e_{a+b\mu}(t, t_0)$; (ii) $v(t) < \Upsilon e_\lambda(t, t_0) + \frac{a^\sharp \epsilon}{\Xi - a^\sharp(c + d \int_0^{\delta_M} H(w)\Delta w)}$ for all $t \in [t_0, +\infty)_{\mathbb{T}}$, where $\Upsilon := a^\sharp \sup_{s \in [t_0 - \tau, t_0]_{\mathbb{T}}} |\psi(s)|$.

Discussion 2. Let $\mathbb{T} = \mathbb{R}$. One can get $p(s) \equiv \alpha + a$. As a consequence, (H_2) can be reduced to

$$(\widehat{H}_2) : \begin{cases} \frac{1}{a^\sharp} \geq \sup_{s \in [t_0, +\infty)} \left\{ \frac{ce^{-\lambda\tau(s)}}{\lambda - (\alpha + a)}, \right. \\ \quad \left. + \frac{de^{-\lambda\delta(s)}}{\lambda - (\alpha + a)} \int_0^{\delta(s)} H(w)dw \right\}, \\ \Xi := -(\alpha + a) \\ > a^\sharp \left(c + d \int_0^{\delta_M} H(w)dw \right). \end{cases}$$

Based on the above discussion, we arrive at Corollary 1.

Corollary 1. For any arbitrary $\epsilon > 0$, let $v(t)$ be the unique solution of

$$\begin{cases} \frac{dv(t)}{dt} = av(t) + cv(t - \tau(t)) \\ \quad + d \int_{t-\delta(t)}^t H(t-s)v(s)ds + \epsilon, \\ v(t_k^+) = a_k v(t_k), \end{cases} \quad (4)$$

with initial condition $v(s) = \psi(s) \in C([t_0 - \tau, t_0], \mathbb{R})$. If there exist constants α and $\lambda < 0$ such that (\widetilde{H}_1) and (\widetilde{H}_2) hold, $v(t) < \Upsilon e^{\lambda(t-t_0)} - \frac{a^\natural \epsilon}{\alpha + a + a^\natural(c + d \int_0^{\delta_M} H(w)dw)}$ holds for all $t \in [t_0, +\infty)$, where Υ, a^\natural are as those defined in Proposition 1.

Discussion 3. Let $\mathbb{T} = \mathbb{Z}$. From Discussion 1, (H_1) implies that $1 + a + b \neq 0$ and $a_k \leq (1 + \alpha)e^{t_k - t_{k-1}}$. Then one gets $p(s) \equiv \alpha + a + b + \alpha(a + b)$. Meanwhile, (H_2) will be reduced to

$$(\widetilde{H}_2) : \begin{cases} \frac{1}{a^\natural} + \lambda > 0, \\ 1 \geq \sup_{s \in [t_0, +\infty)_{\mathbb{T}}} \left\{ \frac{c \exp \int_{s-\tau(s)}^s \log \frac{1}{1+\lambda} \Delta s}{\lambda - (\alpha + a + b + \alpha(a + b))} \right. \\ \quad \left. + \frac{d \exp \int_{s-\delta(s)}^s \log \frac{1}{1+\lambda} \Delta s}{\lambda - (\alpha + a + b + \alpha(a + b))} \right. \\ \quad \left. \cdot \int_0^{\delta(s)} H(w) \Delta w \right\}, \\ \Xi := -(\alpha + a + b + \alpha(a + b)) \\ \quad > a^\natural \left(c + d \sum_{i=0}^{\delta_M} H(i) \right), \end{cases}$$

and so we have Corollary 2.

Corollary 2. For any arbitrary $\epsilon > 0$, let $v(t)$ be the unique solution of

$$\begin{cases} v(t+1) = (a + b + 1)v(t) + cv(t - \tau(t)) \\ \quad + d \int_{t-\delta(t)}^t H(t-s)v(s)\Delta s + \epsilon, \\ v(t_k^+) = a_k v(t_k), \end{cases}$$

with initial condition $v(s) = \psi(s) \in C_{rd}([t_0 - \tau, t_0]_{\mathbb{Z}}, \mathbb{R})$. If there exist constants $\lambda < 0$ and α such that $1 + a + b \neq 0, a_k \leq (1 + \alpha)e^{t_k - t_{k-1}}$ and (\widetilde{H}_2) hold, $v(t) < \Upsilon(1 + \lambda)^{t-t_0} - \frac{a^\natural \epsilon}{\alpha + a + b + \alpha(a + b) + a^\natural(c + d \sum_{i=0}^{\delta_M} H(i))}$ holds for all $t \in [t_0, +\infty)_{\mathbb{Z}}$, where Υ, a^\natural are defined as those in Proposition 1.

Main results. Let $\mathcal{A}_N := I_N \otimes A, \mathcal{A}_P := I_P \otimes A, \mathcal{C}_k^N := I_N \otimes C_k, \mathcal{D}_k := \eta^k \otimes I_n$ and $\mathcal{B}_\Gamma := c(B \otimes \Gamma)$.

For $A \in \mathbb{R}^{n \times n}$, the matrix norm is defined as $\|A\| = \sqrt{\lambda_{\max}(A^T A)}$, where $\lambda_{\max}(A)$ is the maximum eigenvalue of A . The main results are stated in Theorem 1.

Theorem 1. Suppose there exist constants α and $\lambda < 0$ such that (H_1) and (H_2) hold. Then system (1) is exponentially synchronized under impulsive disturbance, where $a := 2K + \hat{\delta} + \varrho + \lambda_{\max}(\mathcal{A}_P^T + \mathcal{A}_P), b := 2K^2(\frac{1}{\delta} + \hat{\varrho} + 1) + (\delta + \varrho + 1)\|\mathcal{A}_P\|^2, c := \frac{K^2}{\delta} + 2K\tau^2(\frac{1}{\delta} + \hat{\varrho} + \frac{1}{K\tau})\mu_M, d := \frac{2\|\hat{\mathcal{B}}_\Gamma\|^2}{\varrho} + (\frac{1}{\varrho} + 1)\|\hat{\mathcal{B}}_\Gamma\|^2\mu_M, a_k := \lambda_{\max}\{(I_P \otimes I_n + (I_P \otimes \mathcal{C}_k)(\hat{\eta}^k \otimes I_n))^T(I_P \otimes I_n + (I_P \otimes \mathcal{C}_k)(\hat{\eta}^k \otimes I_n))\}, \delta, \varrho, \hat{\delta}, \hat{\varrho}$ are positive constants, and $\mu_M = \sup_{s \in \mathbb{T}} \mu(s)$.

Let $\mathbb{T} = \mathbb{R}, \tau(t) \equiv \tau, \delta(t) \equiv \delta_M$ and $H(s) = \text{Dirac}(s - \tau_1)$, where $\text{Dirac}(\cdot)$ is the Dirac function and $0 < \tau_1 < \delta_M$. Then system (1) automatically implies all the results for the systems that are considered in [5].

Compared with [5], our results are more general and avoid separated discussions for $\alpha < 0$ and $\alpha \geq 0$.

Acknowledgements This work was supported by National Natural Science Foundation of China (Grant Nos. 61573005, 11361010, 61573096, 61272530).

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